

Figure 4

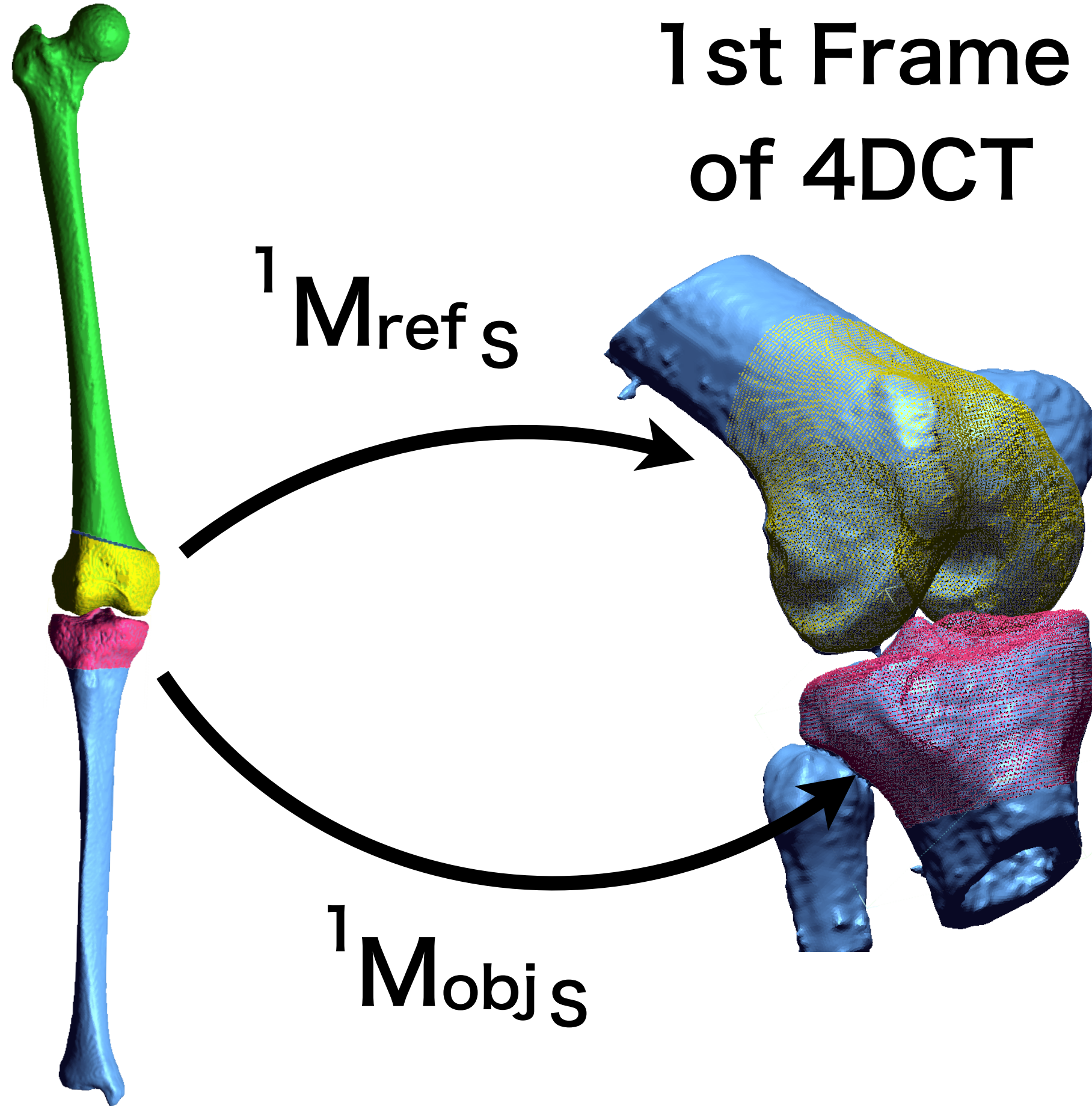
**A**

**Static CT**

**1st Frame  
of 4DCT**

${}^1M_{\text{ref } S}$

${}^1M_{\text{obj } S}$



**B**

$$M = \left( \begin{array}{ccc|c} R^3 & & & d \\ \hline 0 & 0 & 0 & 1 \end{array} \right)$$

**C**

$$M^{\text{inv}} = \left( \begin{array}{ccc|c} {}^tR^3 & & & -{}^tR^3 \cdot d \\ \hline 0 & 0 & 0 & 1 \end{array} \right)$$