

2. Tethering a silkmoth

Manipulations

6.2 Inversion of motor output
6.4 Manipulation of olfactory input

3. Insect-controlled robot
Step sections 3.3 – 3.7

6.5 Manipulation of visual input

5. Odor source
localization experiment
Step sections 5.1 – 5.7

6.1 Manipulation of motor gains
6.3 Manipulation of time delay

Step sections 5.8 – 5.14